

Simulation & Analysis of A 3-Phase 4-Wire System for Evaluation & Mitigation of PQ Problem using Unified Power Quality Conditioner

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ABSTRACT

Electric power is the most essential raw material impacting the bottom line of quality production economically on a commercial scale. It can't typically be stored like other commodities and is essentially required with continuous flow all the time. Electric power can be visualized as the epitome of 'just in time' philosophy used like the components delivered to a production line by a trusted and approved supplier with no facility for 'pre-inspection'. Now a day due to increased use of power electronic device at the distribution level the efficiency and reliability of supply being supplied to consumers is deteriorating. The increased voltage sag, voltage swell, flicker and other power quality problem attract the attention of consumer toward quality of power being supplied to them. Increased PQ problems leads to increased power loss, malfunctioning of electrical equipment and large financial loss, therefore the issue need quick attention. In this paper an effort is made by author to resolve the voltage and current related issues with application of Unified Power Quality Conditioner in the preinstalled distribution networks where design change is not possible. The author used Direct Torque Controlled Induction Motor Drive as a nonlinear load and constant impedance RL load as linear one in a 3-phase, 4-wire distribution system and compared the results with and without use of UPQC.

Keywords: Power Quality, Voltage sag, Voltage swell, DTC induction motor drive, Interruption, UPQC

I. INTRODUCTION

Electricity is the backbone of a country's economy and depict the quality of life of the people residing in it. Its quality and availability at reasonable cost is usually taken for granted, but the real life situation in majority of the cases is entirely different. The general mass of the people have to put up with poor quality and low reliability of electricity and make compromises for survival of the economy and quality of life in most of the developing countries.

The power appliances of the yesteryears had no dearth of materials or electricity and the power equipment could easily withstand dangerous voltage, current, or power transients without objection from any side. Those equipment consumed large amounts of electricity and yet performed well without hurting the consumer expectations. The machines in those days were

conservatively designed with little concern for material, cost or energy wastage and the only consideration in those days was the functioning of the equipment or machine. Today, those mechanically driven equipment have been replaced by power electronic controls and switching devices with focus shifting on energy conservation, automation and cost effectiveness. Power quality, energy conservation and digital economy have become the buzzwords in today's economy and business. Power quality has now become the lifeblood of economy and industrial activity of the societies. It therefore becomes expedient that the quality of energy being supplied to be maintained within acceptable levels and productivity costs be minimized Modern electrical equipment and machines are becoming smaller and smaller in size and becoming more sensitive to disturbance or distortion in the power supply. Another factor that makes PQ issues difficult to grasp is that in some case the equipment misoperates because of its own

power quality problems. It is evident that a few seconds of outage or interruption is sufficient to bring our modern equipment to a screaming stop, resulting in hours of interrupted production which ultimately leads to loss in terms of capital. So if an industry is experiencing 8-15 temporary disturbances every year, costing billions of rupees in lost productivity. This is the reason, power quality related issues are so alarming for power researchers in present scenario.

This work deals with one of the many issues that is the power quality and the mitigation of the problems arising due to lack of it.

II. METHODS AND MATERIAL

A. Power Quality

Power Quality means different things to different people. A very commonly understood definition of power quality is given below:

'Any power problem that results in failure or misoperation of customer equipment manifests itself as an economic burden to the user, or produces negative impacts on the environment.'

The best practice to define it as the capability of an electrical appliance/system to operate efficiently and effectively without disturbing the performance or operation of any other equipment connected directly or in vicinity of it. Majority of electrical appliances and circuits are susceptible to misoperation or complete damage to the device when subjected to one or more power quality disturbances. The electrical appliance might be an electric machine, electronic gadget, PDA, printer, television, industrial equipment or any other household appliance. In last few years the issues related to power quality have gained enormous attention of power researchers because of the damage caused in terms production loss, waste of time, loss of economy etc. etc

B. Sources of Poor Power Quality

PQ problem is an integral issue of voltage, current and frequency concerned abnormalities in an electrical network. An ideal situation demands that, both the network's voltage and current waveform must be of sinusoidal shape. However, the presence of non-linear loads in the network distorts the original shape of the waveforms. In general utility grid is responsible for any deterioration in the voltage quality of an electrical network while the customer's load influences the quality of current. Due to the interactions of these two quantities, the input supply becomes distorted that eventually leads to PQ disturbances in the network.

PQ defects can originate from equipment at consumer's end, or from the supply network. Typical origins of a defect are:

- 1) Sudden connection or disconnection of load
- 2) A power station suddenly going down
- 3) An overcharged line
- 4) A lightning strike
- 5) Harmonic distortions introduced by a generation unit or by a consumer load
- 6) Power electronic speed drives
- 7) SMPS
- 8) Miswired electrical network
- 9) Faults caused by birds and animals
- 10) Power electronic switching
- 11) Severe weather condition
- 12) Inadequate utility services
- 13) Improper circuit design of equipment

C. Need of Power Quality Protection

While power instabilities occur in an electrical system, the consumer end equipment and industrial productivity get affected to a great extent which indirectly adversely affects the economy of a nation. It is already said above that 8 - 12 momentary interruptions a day may cost billions of rupees in a year for a large scale business. For sensitive electronic devices, a momentary disturbance can cause important data corruption, interrupted business communications, proximity effect, irritation for labors working on machines, confusion between system components and equipment failure. A blackout, or power outage, is a complete loss of utility power, whether short- or long-term. Unplanned outages may occur as aging electrical grids and building circuits are overwhelmed by high demand. Blackouts are particularly dangerous at sites where safety or life support rely on power, such as hospitals, treatment centers and power plants.

- Idle workforce and machinery
- Extra investment in terms of overtime working to makeup the loss due to power failure

- Customer dissatisfaction lead to order cancellation and transactions delay
- Revenue and accounting problems such as bills and invoices are not prepared on time, payments slip held up leads to dissatisfaction among workforce etc.. etc..
- Reduced efficiency of workforce

Businesses have huge investment in buildings, staff maintenance, production machineries etc., and power quality protection is a low-priced insurance policy against damages. If due to deviation in the supply production is stopped, major financial loss is occurred. Which ultimately leads to financial starvation for the consumers/businesses and provide hindrance in the overall growth of a nation.

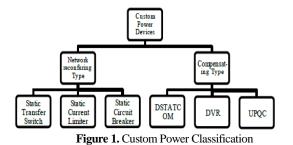
D. Technology for Mitigation of Power Quality Problem

Previously passive filters were being used in power industry to mitigate the disturbances, because performance and quality was not the major concern at that time. But modern scenario is quite different because of increasing demand and modern electronic machinery usage attract the concern of consumers toward the quality of supply due to increased supply fluctuation, breakdown, voltage dips etc. Most newly developed mitigation devices use power electronics. These are commonly referred to as Flexible AC Transmission Systems (FACTS) Devices or Custom Power Devices when applied in the distribution. The FACTS technology opens up new prospects in the field of electrical engineering for controlling VAR and improving the usable available capacity of current as well as new upcoming advance systems. The custom power devices includes, Dynamic Voltage Restorer (DVR), Distribution Static Compensator (DSTATCOM), Unified Power Flow Conditioner (UPFC), Unified Power Quality Conditioner (UPQC)etc. etc..

Mitigation of electrical disturbances can be done from either consumer end or utility end. The custom power devices are mainly divided into two groups:

- 1. Network reconfiguring type
- 2. compensating type

There are two general approaches to the mitigation of power quality problems First methodology used is load conditioning and the other is line conditioning. Load conditioning ensures the immunity of an equipment to withstand against electrical disturbances, allowing it to ride through the disturbances. The other solution is to install line conditioning systems that suppress or counteracts the power system conflicts. However, with the restructuring of power sector, the line conditioning systems plays a vibrant role in enhancing the quality of supply being provided to the consumers.



Network configuring type consist of

- 1) Solid State Current Limiter
- 2) Solid State Transfer Switch
- 3) Solid State Circuit Breaker

Compensating type can be categorized as

- 1) Dynamic Voltage Restorer
- 2) Distribution Static Compensator
- 3) Unified Power Quality Conditioner (UPQC)

E. Unified Power Quality Conditioner: State of Art

It is multi-functional devices that can be used to compensate voltage distortions and prevent harmonic abnormalities from entering into the system. UPQC constructional configuration consist of two voltage source converters sharing the same capacitive DC link. The DC-circuit allows the transfer of real power between shunt and series transformer to control the phase shift of the series voltage. One inverter, called the series inverter is connected via transformers between the source and the common connection point. The other inverter, called the shunt inverter is connected in parallel through the transformers. The series active power filter eliminates voltage flicker/imbalance and shunt filter absorbs the current harmonics contamination produced by the nonlinear loading

General Functions of UPQC

UPQC in general perform following operations when connected to a system:

- 1) Reactive power compensation
- 2) Provide better voltage Regulation
- 3) Compensation for voltage distortions i.e. sag and swell

- 4) Compensation for current harmonics
- 5) Neutral current compensation for a 3-phase 4-wire systems
- 6) Power flow control

The general configuration of UPQC is shown below in figure 2 below

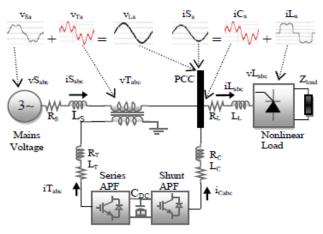
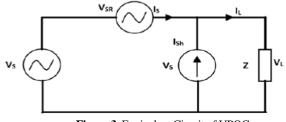


Figure 2. General Configuration of UPQC

F. Mathematical Modeling of UPQC





Where

V_s: Supply Voltage

V_{SR}: Voltage at Series-APF,

V_L: Load voltage

I_{Sh}: Current at Shunt-APF

Voltage distortion, make the system susceptible to negative sequence parameters and harmonic components.

The source voltage, in figure 3 can be represented by following equation:

$$V_S = V_L - V_{SR}$$

In order to obtain sinusoidal shape of constant amplitude, the output voltages of the series-APF must be given by:

$$V_{SR} = (\mathbf{V} - \mathbf{V}_1) \operatorname{Sin}(\omega t + \theta_{1P}) - \mathbf{V}_{Ln}(t) - \sum_{K=2}^{\infty} V_K(t)$$

here.

Where,

 V_1 : Subscript "1" gives positive sequence of voltage

 $\theta_{_{1p}}$: positive sequence phase angle of voltage

 V_{Ln} : Negative sequence component of voltage

The output of shunt-APF contain harmonic, reactive and negative sequence components. For the compensation of such parameters in load current, the output current of shunt

APF I_{sh} is kept equal to the load component as illustrated by below equation:

$$I_{L} = I_{1P} \cos(\omega t + \theta_{1P}) \sin \varphi_{1P} + I_{Ln} + \sum_{K=2}^{\infty} I_{Lk}$$
$$\varphi_{1P} = \phi_{1P} + \theta_{1P}$$

Where,

Subscript "1" represent the positive sequence of all the phase angles

From the above equations it can be seen that the load current is free from harmonic and is sinusoidal in nature having the same phase angle as the phase voltage at the load terminal, Therefore:

$$I_{s} = I_{L} - I_{sh}$$
$$I_{1P} \sin(\omega t - \theta_{1P}) \cos \varphi_{1P}$$

III. RESULTS AND DISCUSSION

G. Steady State Analysis

The UPQC is controlled in such a way that the voltage at the load bus is always sinusoidal and at desired magnitude. In the following analysis the load voltage is assumed to be in phase with terminal voltage even during voltage sag and swell condition. In this particular condition, the series active power filters (APF) could not handle reactive power and the load reactive power is supplied by shunt active power filters (APF) alone

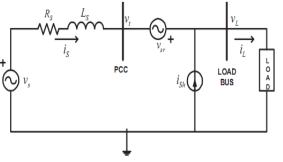


Figure 4. Circuit Showing Source and Load Parameters

The source voltage, terminal voltage at PCC and load voltage are denoted by V_S , V_t and V_L respectively. The source and load currents are denoted by I_S and I_L

respectively. The voltage injected by series APF is denoted by V_{Sr} , whereas the current injected by shunt APF is denoted by i_{Sh} . Taking the load voltage V_L , as a reference phasor and suppose the lagging power factor of the load is $\cos\varphi_L$ then we can write,

$$\begin{split} V_L = V_L \angle 0^{\circ} \\ I_L = I_L \angle -\phi_L \\ V_t = V_L (1+k) \angle 0^{\circ} \end{split}$$

Where factor k represents the fluctuation of source voltage, defined as

$$K = rac{V_t - V_L}{V_L}$$

The voltage injected by series APF must be equal to

$$V_{sr} = V_L - V_t = -kV_L \angle 0^{\circ}$$

The UPQC is assumed to be lossless and therefore, the active power demanded by the load is equal to the active power input at PCC. The UPQC provides a nearly unity power factor source current, therefore, for a given load condition the input active power at PCC can be expressed by the following equations,

$$P_{t} = P_{L}$$

$$V_{t}i_{s} = V_{L}i_{L}\cos\varphi_{L}$$

$$V_{L}(1+k)i_{s} = V_{L}i_{L}\cos\varphi_{L}$$

$$i_{s} = i_{L} / (1+k)^{*}\cos\varphi_{L}$$

The above equation suggests that the source current i_s depends on the factor k, since Φ_L and i_L are load characteristics and are constant for a particular type of load. The complex power absorbed by the series APF can be expressed as

$$S_{sr} = V_{sr}i_{s}^{*}$$

$$P_{Sr} = V_{Sr}i_{s}\cos\varphi_{s} = -kV_{L}i_{S}\cos\varphi_{s}$$

$$Q_{Sr} = V_{Sr}i_{S}\sin\varphi_{s}$$

 $\varphi_s = 0$, since UPQC is maintaining unity power factor, Therefore the above equations become

$$S_{sr} = V_{sr}i_s^*$$

$$P_{Sr} = V_{Sr}i_s = -kV_Li_s$$

$$Q_{Sr} \cong 0$$

The complex power absorbed by the shunt APF can be expressed as,

$$S_{sh} = V_L i_{sh}^*$$

The current provided by the shunt APF, is the difference between the input source current and the load current,

which includes the load harmonics current and the reactive current. Therefore, we can write,

$$i_{Sh} = i_{S} - i_{L}$$

$$i_{Sh} = i_{S} \angle 0^{\circ} - i_{L} \angle -\varphi_{L}$$

$$i_{Sh} = i_{S} - i_{L} (\cos \varphi_{L} - j\sin \varphi_{L})$$

$$P_{Sh} = V_{L} i_{Sh} \cos \varphi_{Sh} = V_{L} (i_{S} - i_{L} \cos \varphi_{L})$$

$$Q_{Sh} = V_{L} i_{Sh} \sin \varphi_{Sh}$$

From above equations the control action of active and reactive power by UPQC can easily be calculated.

H. Test System Under Consideration

Simulation model of 3- phase, 4-wire distribution system having 11kV, 50Hz supply and containing constant impedance RL load and DTC induction motor drive as nonlinear load with UPQC. For the generation of reference signals for both shunt and series active filters of UPQC, an approach based on two closed loop PI controllers for shunt and series active power filters (APFs) utilization, and other strategy unit vector template generation is implemented. The output from generating unit is fed to the primary of the three winding transformer. Further two parallel feeders of 11kV each are drawn. In one of the feeders UPQC is connected with a linear and nonlinear load and other feeder is kept as it is. The modeling and simulation of the system is done in MATLAB/SIMULINK software. The parameters

of the test system are as listed in the table 1 below:

Table 1Parameters for the Test System		
	Quantities	
1.	Inverter	IGBT based, 3-arm, 6-Pulse,
	parameters	Carrier Frequency=1080 Hz,
		Sample Time=5 µs
2.	PI controller	KP=0.5, Ki=1000 for series
		control Kp=0.5, Ki=1000 for
		shunt control, Sample
		time=50 μs
3.	Constant	Active power = 1kW,
	Impedance	Inductive Reactive
	RL Load	Power=400 VAR
4.	Motor Load	Voltage Vrms=11kV,
		Frequency 50 Hz
5.	Transformer	Y/Δ/Δ 11/115/115kV
	1	

6.	Transformer 2	Δ/Y 115/11kV
7.	Transformer 3	Δ/Y 11/6.6kV

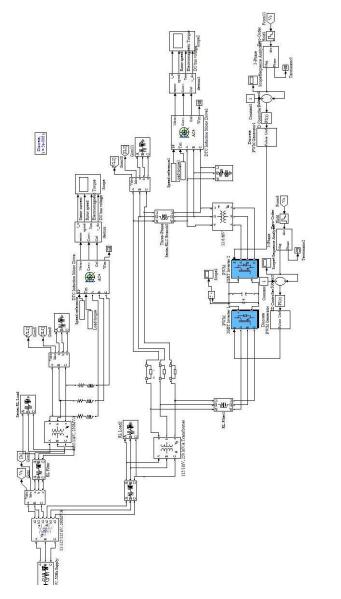


Figure 5. Matlab Model of Distribution Network Carrying Linear and Nonlinear Load With and Without UPQC

I. Simulation Results when DTC Induction Motor Drive and Constant Impedance RL Load is Used

Here an ideal three-phase sinusoidal supply voltage is applied to a constant impedance RL load and a non-linear load (Direct Torque control Induction motor drive) injecting current and voltage harmonics into the system. The voltage and current waveform at each loading is carefully observed. The total harmonic distortion (THD) associated with current and voltage waveform at linear and nonlinear loading is also observed.

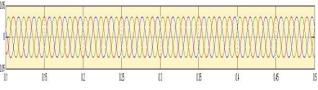


Figure 6(a). Voltage Waveform Across Three Phase RL Load Without UPQC

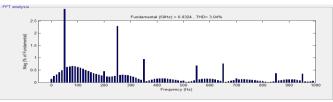
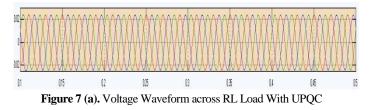


Figure 6(b). Total Harmonic Distortion in Voltage Across Three Phase RL Load Without UPQC

Figure 6 (a) shows the voltage across three-phase constant impedance RL load before compensation without UPQC and figure 6 (b) shows THD level for uncompensated load voltage. The total harmonic distortion in the load voltage is found to be 3.04 %.



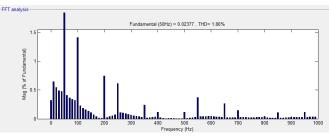
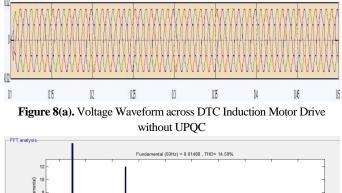


Figure 7(b). Total Harmonic Distortion in Voltage Waveform across RL Load With UPQC

Figure 7 (a) shows the compensated voltage across threephase constant impedance RL load and figure 7 (b) shows THD level for compensated load voltage. The total harmonic distortion in the load voltage is found to be 1.86 %. It can be seen the distortion in voltages has dropped to an acceptable limit.



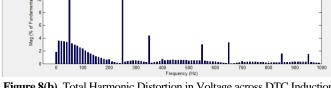


Figure 8(b). Total Harmonic Distortion in Voltage across DTC Induction Motor Drive Without UPQC

Figure 8 (a) shows the uncompensated voltage across DTC Induction motor drive load and figure 8 (b) shows THD level for uncompensated load voltage. The total harmonic distortion in the uncompensated voltages is found to be 14.59 %.

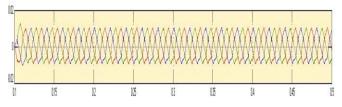


Figure 9(a). Voltage Waveform Across DTC induction Motor Drive With UPQC

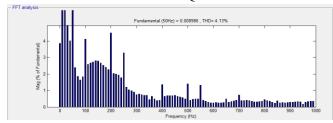


Figure 9(b). Total Harmonic Distortion in Voltage Across DTC induction Motor Drive With UPQC

Figure 9 (a) shows the compensated voltage across DTC Induction motor drive load with the application of UPQC and figure 9 (b) shows THD level for the compensated load voltage. The total harmonic distortion in the uncompensated voltages is found to be 4.13 %. It shows that there is appreciable drop in THD level with the application of UPQC with nonlinear loading.

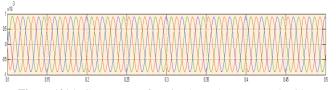


Figure 10(a). Current Waveform in Three Phase RL Load Without UPQC

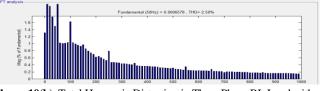
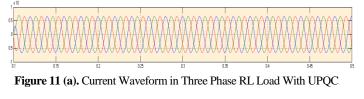


Figure 10(b). Total Harmonic Distortion in Three Phase RL Load without UPQC

Figure 10 (a) shows the uncompensated current in constant impedance RL load, and figure 10 (b) shows the total harmonic distortion level in the load current. The total harmonic distortion in the uncompensated load current is found to be 2.50 %.



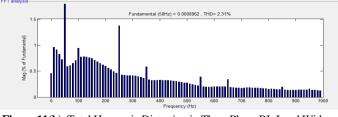


Figure 11(b). Total Harmonic Distortion in Three Phase RL Load With UPQC

Figure 11(a) shows the compensated current in constant impedance RL load, and figure 11 (b) shows the total harmonic distortion level in the compensated current. The total harmonic distortion in the load current after compensation is found to be 2.31 %. This is a very small level of compensation or correction which shows that with linear loading the distortion in the current or voltages is not very large. Therefore it can be said that linear loading in not an issue to worry in a 3-phase, 4- wire distribution system

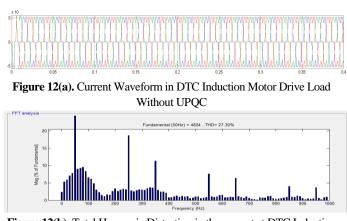
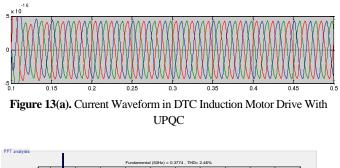


Figure 12(b). Total Harmonic Distortion in the current at DTC Induction Motor Drive Load Without UPQC

Figure 12(a) shows the uncompensated current in DTC Induction motor drive load, it is seen that current profile shown in the figure 12(a) is not perfect sinusoidal. Figure 12 (b) shows the total harmonic distortion level in the uncompensated current. The total harmonic distortion in the current without any compensation is found to be 27.30 %. This shows that distortion in the current with nonlinear loading is very large and require serious attention as it leads to deterioration in the performance of the load connected to it.



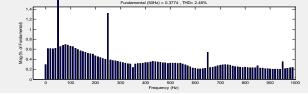


Figure 13(b). Total Harmonic Distortion in the current at DTC Induction Motor Drive With UPQC

Figure 13 (a) shows the compensated current in DTC Induction motor drive load, it is seen that current profile shown in the figure 13 (a) is near perfect sinusoid. Figure 13 (b) shows the total harmonic distortion level in the compensated current with the application of UPQC. The total harmonic distortion in the current without any compensation is found to be 2.46 %. This shows that distortion level in the current with the application of compensating device as UPQC has been resolved to a large extent. This suffice the purpose of the writing this thesis by selecting Unified power quality conditioner for PQ mitigation.

IV. CONCLUSION

Here a general review of what theoretical mitigation methods are available for the different types of power quality disturbances is presented. Mitigation on design level leads to high input capital and consume lot of effort and time therefore, the focus of the study lies on mitigation devices rather than mitigation through the design of the power system, production facilities and loads connected to it. . Constant impedance RL load is used as linear load and direct torque controlled induction motor drive is used as non-linear one. It is found that distortion in voltages and currents with RL loading is very small and lies in acceptable limit, does not require much attention. But when it comes to nonlinear loading like DTC induction motor drive is the case the distortion in the voltage and current profile is quite appreciable, which cannot be ignored. When UPQC is used as compensating device, the substantial improvement in voltage and current profile as well as in THD level is observed.

Therefore, UPQC is considered to be an efficient solution for mitigation of power quality disturbances in non-linear loading. Unified power quality conditioner is capable of reducing the level of THD in the case of networks which are connected to the harmonics generating load (like ASD).

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